

ON OPTIMAL DIVIDEND STRATEGIES IN THE COMPOUND POISSON MODEL

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ABSTRACT

The optimal dividend problem goes back to a paper that Bruno De Finetti presented to the International Congress of Actuaries in New York (1957). For a stock company that pays dividends to its shareholders, what is the strategy that maximizes the expectation of the discounted dividends (until possible ruin)? Jeanblanc-Picqué and Shiryaev (1995) and Asmussen and Taksar (1997) solved the problem in the Brownian motion model, when a ceiling is imposed for the dividend rate. Here we study the problem with the Brownian motion generalized to a compound Poisson process. In particular, we derive a rule for deciding between plowback and dividend payout, which is a key issue in corporate finance.

1. INTRODUCTION

The optimal dividend problem goes back to Bruno De Finetti (1957), who presented his paper at the 15th International Congress of Actuaries in New York City. In classical risk theory, the problem is to calculate the probability of ruin; hopefully, ruin does not occur, and thus the surplus grows indefinitely. As this is not realistic, De Finetti suggested that a company would seek to maximize the expectation of the present value of all dividends before possible ruin. He showed that, under the assumption that the surplus of the company is a discrete process with steps of size plus or minus one only, the optimal dividend-payment strategy is a *barrier strategy*: that is, any surplus above a certain level would be paid as dividends to the shareholders of the company.

In a series of papers, Karl Borch followed up on these ideas and made them accessible to economists as well. Borch's ideas are summarized in Chapter 6 of Seal (1969); see also Borch (1974, 1990). A first treatment of the optimal dividend problem in the classical compound Poisson model can be found in Section 6.4 of Bühlmann (1970).

Jeanblanc-Picqué and Shiryaev (1995) and Asmussen and Taksar (1997) modified the problem. In the Brownian motion model, they considered only dividend strategies with a *ceiling* for the dividend rate. They showed that the optimal dividend strategy is now a *threshold strategy*, that is, dividends should be paid out at the maximal admissible rate as soon as the surplus exceeds a certain threshold. Some down-to-earth calculations for this model can be found in Gerber and Shiu (2006). The purpose of this paper is to examine the analogous questions in the compound Poisson model.

The theoretical foundations are laid in Sections 3 and 4 of the paper. It is shown that the maximal value function can be characterized by the Hamilton-Jacobi-Bellman equation. A rule for deciding between plowback and dividend payout is derived. Sections 5 and 6 discuss the value of a threshold strategy, that is, the expectation of the discounted dividends until ruin, if a threshold strategy is applied. Explicit results are obtained in the case of exponential claim amount distributions. In Section 7 results for the Brownian motion model are retrieved as limits. For the case of an exponential claim

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amount distribution, it is shown that the optimal dividend strategy is a threshold strategy, and the optimal threshold is determined. Conditions are given under which the latter is positive. Section 10 shows how the expected present value of 1 due at the time of ruin, under a threshold strategy, can be calculated. In the appendices, results of Sections 6 and 10 are generalized to the case where the claim amount distribution is a mixture of exponential distributions.

The results in this paper can be extended in various directions. For example, see Lin and Pavlova (2006).

2. PROBLEM FORMULATION

In the classical model of risk theory, the *surplus process* $\{U(t)\}$ of an insurance company is given by

$$U(t) = U(0) + ct - S(t), \quad t \geq 0. \quad (2.1)$$

The premiums are received continuously at a constant rate c , and the *aggregated claims process* $\{S(t)\}$ is a compound Poisson process with claim frequency λ and individual claim amount probability density function $p(y)$, $y \geq 0$.

We now enrich the model. We assume that the insurance company is a stock company, and dividends are paid to the shareholders according to some *dividend strategy*. Let $D(t)$ denote the aggregated dividends paid between time 0 and time t , and $X(t)$ be the company's surplus, net of dividend payments, at time t . Thus,

$$X(t) = U(t) - D(t), \quad t \geq 0. \quad (2.2)$$

Let

$$T = \inf\{t \geq 0 | X(t) < 0\} \quad (2.3)$$

be the *time of ruin*, and

$$D = \int_0^T e^{-\delta t} dD(t) \quad (2.4)$$

be the present value of all dividends until ruin, where $\delta > 0$ is the force of interest for valuation. The company seeks to maximize the expectation of the random variable D .

We study this optimization problem under the constraint that only dividend strategies with dividend rate bounded by a ceiling are admissible. We assume that the ceiling is less than the premium rate. Thus, the constraint is

$$dD(t) \leq \alpha dt, \quad (2.5)$$

where $\alpha \in (0, c)$ is the dividend-rate ceiling.

We do not assume the positive security-loading condition: that is, the condition

$$c > \lambda \int_0^\infty yp(y) dy \quad (2.6)$$

may or may not be fulfilled.

3. THE HJB EQUATION

Let $V(x)$ denote the supremum of $E[D]$, where the supremum is taken over all admissible dividend strategies, and x is the company's initial surplus,

$$x = X(0) = U(0). \quad (3.1)$$

The function $V(x)$ satisfies the so-called *Hamilton-Jacobi-Bellman* (HJB) functional equation:

$$\text{Max}_{0 \leq r \leq \alpha} \{r + (c - r)V'(x)\} - (\lambda + \delta)V(x) + \lambda \int_0^x V(x - y)p(y) dy = 0, \quad x \geq 0. \quad (3.2)$$

Equation (3.2) can be explained by *Bellman's dynamic programming principle*. We consider the “small” time interval between 0 and ε , $\varepsilon > 0$, and the following dividend strategy. Suppose that between time 0 and time ε , dividends are paid at rate r , and thereafter, an optimal strategy is applied. By conditioning on whether there is a claim in this time interval and on the amount of the claim if it occurs, we see that the expectation of the present value of all dividends until ruin is

$$r\varepsilon + e^{-\delta\varepsilon}[(1 - \lambda\varepsilon)V(x + (c - r)\varepsilon) + \lambda\varepsilon \int_0^x V(x - y)p(y) dy] + o(\varepsilon), \quad (3.3)$$

which is

$$V(x) + [r + (c - r)V'(x) - (\lambda + \delta)V(x) + \lambda \int_0^x V(x - y)p(y) dy]\varepsilon + o(\varepsilon). \quad (3.4)$$

Because $V(x)$ is the optimal value, it must be equal to the maximum value of expression (3.4), where $r \in [0, \alpha]$. Thus, the maximum of the expression within the brackets in expression (3.4) must be zero, and hence we obtain the functional equation (3.2). On the left-hand side of equation (3.2), the expression to be maximized is

$$r[1 - V'(x)]$$

for $r \in [0, \alpha]$. Thus, the optimal dividend rate at time 0 is

$$\begin{aligned} r &= 0 & \text{if } V'(x) > 1, \\ r &= \alpha & \text{if } V'(x) < 1. \end{aligned} \quad (3.5)$$

If $V'(x) = 1$, the dividend rate r can be any value between 0 and α . Then, at time $t \in (0, T)$, the optimal dividend rate is

$$\begin{aligned} r &= 0 & \text{if } V'(X(t)) > 1, \\ r &= \alpha & \text{if } V'(X(t)) < 1. \end{aligned} \quad (3.6)$$

Such a dividend strategy has the character of a *bang bang strategy*.

Formula (3.6) has the following interpretation. If $V'(X(t)) > 1$, the company is “efficient,” and hence it is advantageous to pay no dividends and leave the funds with the company. On the other hand, if $V'(X(t)) < 1$, the company is “inefficient,” and hence it is best to pay out as many dividends as allowable. The problem of deciding between plowback and dividend payout is a classical problem in *corporate finance*. Here we have derived a solution in a continuous-time model.

In the next section we show that a strategy with $E[D]$, as a function of the initial surplus x , satisfying the HJB equation (3.2) is indeed an optimal strategy.

4. VERIFICATION OF OPTIMALITY

For some given dividend strategy, let

$$v(x) = E[D], \quad (4.1)$$

a function of the initial surplus x . Suppose that $v(x)$ satisfies the HJB equation (3.2). Consider any other dividend strategy, with dividend rate $r(t)$ and surplus $X(t)$ at time t . We claim that

$$\mathbb{E} \left[\int_0^T e^{-\delta t} r(t) dt \middle| X(0) = x \right] \leq v(x). \quad (4.2)$$

From this, it follows that $v(x) = V(x)$, and hence the given strategy is optimal.

To show inequality (4.2), we consider the *compensated process*

$$\left\{ e^{-\delta t} v(X(t)) - \int_0^t e^{-\delta \tau} \kappa(\tau) d\tau \right\}, \quad (4.3)$$

for $0 \leq t \leq T$, where

$$\kappa(\tau) = \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} \mathbb{E}[e^{-\delta \varepsilon} v(X(\tau + \varepsilon)) - v(X(\tau)) | X(\tau)]. \quad (4.4)$$

(Note that $\kappa(\tau)$ plays the role of a risk premium rate in the theory of *life contingencies*.) Because (4.3) is a martingale, we have

$$\mathbb{E} \left[e^{-\delta(t \wedge T)} v(X(t \wedge T)) - \int_0^{t \wedge T} e^{-\delta \tau} \kappa(\tau) d\tau \middle| X(0) = x \right] = v(x), \quad (4.5)$$

which implies

$$-\mathbb{E} \left[\int_0^{t \wedge T} e^{-\delta \tau} \kappa(\tau) d\tau \middle| X(0) = x \right] \leq v(x). \quad (4.6)$$

By a calculation similar to how we obtained expression (3.4), we see that the right-hand side of (4.4) is

$$[c - r(\tau)]v'(X(\tau)) - (\lambda + \delta)v(X(\tau)) + \lambda \int_0^{X(\tau)} v(X(\tau) - y)p(y) dy. \quad (4.7)$$

Because the function $v(x)$ satisfies the HJB equation (3.2), the sum of $r(\tau)$ and expression (4.7) must be nonpositive, that is,

$$r(\tau) + \kappa(\tau) \leq 0.$$

From this and inequality (4.6) we gather that

$$\mathbb{E} \left[\int_0^{t \wedge T} e^{-\delta \tau} r(\tau) d\tau \middle| X(0) = x \right] \leq v(x). \quad (4.8)$$

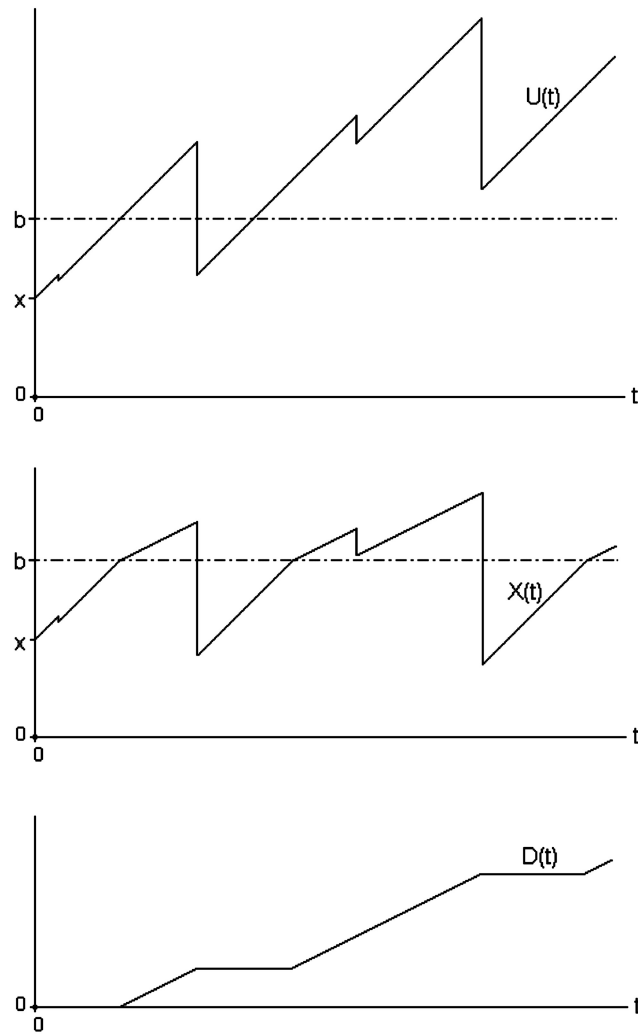
Finally, inequality (4.2) is obtained in the limit $t \rightarrow \infty$.

5. THRESHOLD STRATEGIES

If the solution of equation (3.2) has the property that $V'(x) > 1$ for $x < b$ and $V'(x) < 1$ for $x > b$, for some number b , then the optimal dividend strategy is particularly appealing: Whenever $X(t) < b$, no dividends are paid, and whenever $X(t) > b$, dividends are paid at the maximal rate α . We shall call such a dividend strategy a *threshold strategy*. Figure 1 illustrates how $X(t)$ and $D(t)$ are obtained from a given sample path of $\{X(t)\}$. Note that the (modified) surplus process $\{X(t)\}$ undergoes a refraction at the level b .

Threshold strategies are of interest, even in cases where the optimal dividend strategy is not of this form. Let $V(x; b)$ denote the expectation of the present value of all dividends until ruin, where x is the initial surplus and b is the threshold. As a function of x , $V(x; b)$ satisfies the following integro-differential equations:

Figure 1
Illustration of a Threshold Strategy



$$cV'(x; b) - (\lambda + \delta)V(x; b) + \lambda \int_0^x V(x - y; b)p(y) dy = 0, \quad 0 < x < b, \quad (5.1)$$

$$\alpha + (c - \alpha)V'(x; b) - (\lambda + \delta)V(x; b) + \lambda \int_0^x V(x - y; b)p(y) dy = 0, \quad x > b. \quad (5.2)$$

Both equations can be obtained by arguments that are similar to the one used to justify (3.2).

For $x \rightarrow \infty$, $V(x; b)$ approaches the present value of a perpetuity with continuous payments at rate α ,

$$\lim_{x \rightarrow \infty} V(x; b) = \frac{\alpha}{\delta}. \quad (5.3)$$

Finally, it follows from

$$e^{-(\delta+\lambda)y/c}V(b; b) < V(b - y; b) < V(b; b), \quad 0 < y \leq b, \quad (5.4)$$

that $V(x; b)$ is a continuous function of x at $x = b$. This, together with formulas (5.1)–(5.3), determines the function $V(x; b)$, $x \geq 0$. The derivative, $V'(x; b)$, is not necessarily continuous at $x = b$. In fact, it follows from equations (5.1) and (5.2) that

$$cV'(b-; b) = (c - \alpha)V'(b+; b) + \alpha. \quad (5.5)$$

The integro-differential equation

$$ch'(x) - (\lambda + \delta)h(x) + \lambda \int_0^x h(x-y)p(y) dy = 0, \quad x > 0, \quad (5.6)$$

has, apart from a constant factor, a unique solution $h(x)$. It follows from this and equation (5.1) that

$$V(x; b) = \gamma h(x), \quad 0 \leq x \leq b, \quad (5.7)$$

where γ does not depend on x .

REMARKS

1. Three equivalent expressions for $h(x)$ can be found in Chan, Gerber, and Shiu (2006). There is a discussion on $h(x)$ in Lin, Willmot, and Drekić (2003, Section 4).
2. Consider the limiting case $\alpha = c$, where the threshold becomes a barrier. (See the figure on page 169 of Bühlmann [1970].) Then, condition (5.5) becomes

$$V'(b-; b) = 1, \quad (5.8)$$

and hence (5.7) implies that

$$V(x; b) = \frac{h(x)}{h'(b)}, \quad 0 \leq x \leq b, \quad (5.9)$$

which is formula (D₅) on page 172 of Bühlmann and formula (1.19) of Zhou (2005). Formula (5.8) is formula (7.4) of Gerber and Shiu (1998).

6. EXPONENTIAL CLAIM DENSITY

Here we assume that the individual claim amounts are exponentially distributed,

$$p(x) = \beta e^{-\beta x}, \quad x > 0. \quad (6.1)$$

Then, the integro-differential equation (5.6) can be converted to a linear differential equation with constant coefficients, because

$$\left(\frac{d}{dx} + \beta \right) \int_0^x h(x-y)p(y) dy = \beta h(x), \quad x \geq 0. \quad (6.2)$$

To verify (6.2), we observe that the convolution integral in it can be written as

$$\int_0^x h(y)p(x-y) dy, \quad (6.3)$$

whose derivative with respect to x is

$$h(x)p(0) + \int_0^x h(y)p'(x-y) dy = \beta \left[h(x) - \int_0^x h(y)p(x-y) dy \right].$$

Thus, applying the operator $(d/dx + \beta)$ to equation (5.6) yields the differential equation

$$ch''(x) + (\beta c - \lambda - \delta)h'(x) - \beta \delta h(x) = 0. \quad (6.4)$$

The solutions of equation (6.4) are given by

$$h(x) = C_0 e^{rx} + C_1 e^{sx}, \quad (6.5)$$

where $r > 0$ and $s < 0$ are the roots of the characteristic equation

$$c\xi^2 + (\beta c - \lambda - \delta)\xi - \beta\delta = 0. \quad (6.6)$$

The expression on the left-hand side of equation (6.6) is $-\beta\delta$ for $\xi = 0$ and $\beta\lambda$ for $\xi = -\beta$. It follows that $-\beta < s < 0$, which shows that $\beta + s$ is positive. Substituting (6.5) in equation (5.6) and equating the coefficient of $e^{-\beta x}$ with 0, we have

$$\lambda\beta \left(\frac{C_0}{r + \beta} + \frac{C_1}{s + \beta} \right) = 0.$$

Thus, $h(x)$ is proportional to $(r + \beta)e^{rx} - (s + \beta)e^{sx}$. From this and (5.7), we can write

$$V(x; b) = \gamma[(r + \beta)e^{rx} - (s + \beta)e^{sx}], \quad 0 \leq x \leq b, \quad (6.7)$$

where γ does not depend on x . In the limiting case $\alpha = c$, it follows from (5.8) that

$$\gamma = \frac{1}{(\beta + r)re^{rb} - (\beta + s)se^{sb}}, \quad (6.8)$$

which agrees with formula (7.8) in Gerber and Shiu (1998).

Applying the operator $(d/dx + \beta)$ to equation (5.2) and rearranging yields the differential equation

$$(c - \alpha)V''(x; b) + [\beta(c - \alpha) - \lambda - \delta]V'(x; b) - \beta\delta V(x; b) + \beta\alpha = 0, \quad x > b, \quad (6.9)$$

of which the constant function α/δ is a particular solution. From this and (5.3), we gather that

$$V(x; b) = \frac{\alpha}{\delta} + De^{ux}, \quad x \geq b, \quad (6.10)$$

where u is the negative solution of

$$(c - \alpha)\xi^2 + [\beta(c - \alpha) - \lambda - \delta]\xi - \beta\delta = 0. \quad (6.11)$$

To determine γ and D , we need two conditions. From the continuity condition,

$$V(b-; b) = V(b+; b),$$

we have

$$\gamma[(r + \beta)e^{rb} - (s + \beta)e^{sb}] = \frac{\alpha}{\delta} + De^{ub}. \quad (6.12)$$

For a second condition, we observe that the convolution integral in equation (5.2) is

$$\begin{aligned} \int_0^x V(z; b)p(x - z) dz &= \gamma \int_0^b [(r + \beta)e^{rz} - (s + \beta)e^{sz}]p(x - z) dz + \int_b^x \left[\frac{\alpha}{\delta} + De^{uz} \right] p(x - z) dz \\ &= \beta e^{-\beta x} \left\{ \gamma(e^{(\beta+r)b} - e^{(\beta+s)b}) + \frac{\alpha}{\delta} \frac{1}{\beta} (e^{\beta x} - e^{\beta b}) + D \frac{1}{\beta + u} [e^{(\beta+u)x} - e^{(\beta+u)b}] \right\}. \end{aligned}$$

All other terms in equation (5.2) do not involve the exponential function $e^{-\beta x}$. By setting the coefficient of $e^{-\beta x}$ to 0, and then canceling the factor $\beta e^{\beta b}$, we obtain our second condition:

$$\gamma(e^{rb} - e^{sb}) - \frac{\alpha}{\delta\beta} - \frac{De^{ub}}{\beta + u} = 0. \quad (6.13)$$

It follows from equations (6.12) and (6.13) that

$$\gamma = \frac{-u}{\beta} \frac{\alpha}{\delta} \frac{1}{(r - u)e^{rb} - (s - u)e^{sb}}.$$

Thus,

$$V(x; b) = \frac{-u}{\beta} \frac{\alpha}{\delta} \frac{(\beta + r)e^{rx} - (\beta + s)e^{sx}}{(r - u)e^{rb} - (s - u)e^{sb}}, \quad 0 \leq x \leq b. \quad (6.14)$$

Finally,

$$V(x; b) = \frac{\alpha}{\delta} [1 - e^{u(x-b)}] + V(b; b)e^{u(x-b)}, \quad x \geq b. \quad (6.15)$$

Observe that

$$V(0; 0) = \frac{-u}{\beta} \frac{\alpha}{\delta}. \quad (6.16)$$

Because $V(0; 0)$ is less than α/δ , the present value of a perpetuity with payment rate α , we must have $0 < -u/\beta < 1$. An algebraic verification is as follows. The expression on the left-hand side of equation (6.11) is negative for $\xi = 0$ and positive for $\xi = -\beta$. Hence u , the negative solution of equation (6.11), is between $-\beta$ and 0.

In Appendix A, it is shown how $V(x; b)$ can be calculated when the claim amount density is a mixture of exponential densities.

7. THE BROWNIAN MOTION MODEL

We consider the model where the difference between aggregate premiums and claims is a Brownian motion with constant drift and diffusion parameters, μ and σ , respectively. Thus,

$$U(t) = U(0) + \mu t + \sigma W(t), \quad (7.1)$$

where $\{W(t)\}$ is a standard Brownian motion (Wiener process). This model can be viewed as the limit of a family of compound Poisson models with exponential claim amount densities, and in this way many formulas in Gerber and Shiu (2006) can be obtained as limiting results.

By equating the drift and the variance per unit time, we obtain the conditions

$$\mu = c - E[S(1)] = c - \frac{\lambda}{\beta}, \quad (7.2)$$

and

$$\sigma^2 = \text{Var}[S(1)] = \frac{2\lambda}{\beta^2}. \quad (7.3)$$

Then, in the limit $\lambda \rightarrow \infty$, $\beta \rightarrow \infty$, $c \rightarrow \infty$, while under constraints (7.2) and (7.3), the Brownian motion model with parameters μ and σ is obtained.

In the limit, the quadratic equation (6.6) for $r > 0$ and $s < 0$ becomes

$$\frac{\sigma^2}{2} \xi^2 + \mu \xi - \delta = 0, \quad (7.4)$$

while the quadratic equation (6.11) for $u < 0$ becomes

$$\frac{\sigma^2}{2} \xi^2 + (\mu - \alpha)\xi - \delta = 0. \quad (7.5)$$

From (6.14), we obtain in the limit the formula

$$V(x; b) = (-u) \frac{\alpha}{\delta} \frac{e^{rx} - e^{sx}}{(r - u)e^{rb} - (s - u)e^{sb}} \quad \text{for } 0 \leq x \leq b, \quad (7.6)$$

which is formula (2.22) in Gerber and Shiu (2006). Formally, formula (6.15) remains valid in the limit.

8. OPTIMAL THRESHOLD STRATEGIES

In some situations the optimal dividend strategy is a threshold strategy. Let b^* denote the optimal threshold. Two cases have to be distinguished:

1. If

$$V'(x; 0) < 1 \quad \text{for } x > 0, \quad (8.1)$$

then the threshold strategy with $b^* = 0$ is optimal.

2. If the optimal strategy is the threshold strategy with $b^* > 0$, we must have

$$V'(x; b^*) > 1 \quad \text{for } x < b^*, \quad (8.2)$$

$$V'(x; b^*) < 1 \quad \text{for } x > b^*. \quad (8.3)$$

Formula (5.5) shows that $V'(b-; b)$ is a weighted average of $V'(b+; b)$ and 1. Hence, the two quantities $V'(b-; b)$ and $V'(b+; b)$ are both less than 1, both greater than 1, or both equal to 1. From this fact and inequalities (8.2) and (8.3), we gather that

$$V'(b^*-; b^*) = 1, \quad (8.4)$$

$$V'(b^*+; b^*) = 1. \quad (8.5)$$

Thus, the optimal threshold b^* can be obtained from either one of these two equivalent equations. By writing γ in (5.7) as $V(b; b)/h(b)$, we see a third method to obtain b^* . It is also the value of b that maximizes

$$V(x; b) = V(b; b) \frac{h(x)}{h(b)}, \quad 0 \leq x \leq b. \quad (8.6)$$

Furthermore, we remark that

$$V(x; b^*) = \frac{h(x)}{h'(b^*)}, \quad 0 \leq x \leq b^*. \quad (8.7)$$

To prove (8.7), we differentiate (5.7) with respect to x , and then set $x = b = b^*$. Applying (8.4) yields $\gamma = 1/h'(b^*)$, and thus we have (8.7).

REMARK

Note the difference between formulas (8.7) and (5.9). Formula (5.9) is the valuation formula for a barrier strategy, that is, for the limiting case $\alpha = c$. In contrast to formula (8.7), formula (5.9) holds for *arbitrary* values of b .

9. OPTIMAL DIVIDEND STRATEGIES FOR EXPONENTIAL CLAIMS

In this section we show that for an exponential claim density, the optimal dividend strategy is indeed a threshold strategy. From (6.15), it follows that

$$V'(x; b) = (-u) \left[\frac{\alpha}{\delta} - V(b; b) \right] e^{u(x-b)}, \quad x > b. \quad (9.1)$$

Thus, $b^* = 0$ if condition (8.1) is satisfied or, equivalently, if

$$(-u) \left[\frac{\alpha}{\delta} - V(0; 0) \right] \leq 1, \quad (9.2)$$

which, by (6.16), is

$$(-u) \frac{\alpha}{\delta} \left[1 + \frac{u}{\beta} \right] \leq 1. \quad (9.3)$$

Now, suppose that the inequalities in (9.2) and (9.3) are changed from “ \leq ” to “ $>$ ”. From (8.5) and (9.1), we get the condition for b^* :

$$(-u) \left[\frac{\alpha}{\delta} - V(b^*; b^*) \right] = 1, \quad (9.4)$$

that is, b^* is the solution of the equation

$$V(b^*; b^*) = \frac{\alpha}{\delta} + \frac{1}{u}. \quad (9.5)$$

From this and (6.15), it follows that

$$V(x; b^*) = \frac{\alpha}{\delta} + \frac{1}{u} e^{u(x-b^*)}, \quad x \geq b^*. \quad (9.6)$$

It remains to verify that conditions (8.2) and (8.3) are satisfied. For condition (8.3), this is easy, because it follows from (9.6) that

$$V'(x; b^*) = e^{u(x-b^*)} < 1 \quad \text{for } x > b^*. \quad (9.7)$$

To show that condition (8.2) holds, we show that

$$V''(x; b^*) < 0 \quad \text{for } 0 \leq x < b^*. \quad (9.8)$$

Note that differentiating (6.7) twice yields

$$V''(x; b) = \gamma[r^2(r + \beta)e^{rx} - s^2(s + \beta)e^{sx}], \quad 0 < x < b. \quad (9.9)$$

This is an increasing function because it is the difference of an increasing and a decreasing function; hence its maximum value for $0 \leq x \leq b$ is attained at $x = b$. Consequently, inequality (9.8) is equivalent to the condition that

$$V''(b^*-; b^*) \leq 0. \quad (9.10)$$

From (6.4), with $h(x)$ replaced by $V(x; b^*)$, and (8.4), we have

$$cV''(b^*-; b^*) = \beta\delta V(b^*; b^*) - (\beta c - \lambda - \delta), \quad (9.11)$$

and from (6.9) and (8.5), we have

$$(c - \alpha)V''(b^*+; b^*) = \beta\delta V(b^*; b^*) - (\beta c - \lambda - \delta). \quad (9.12)$$

Hence, (9.10) is the same as the condition that

$$V''(b^*+; b^*) \leq 0, \quad (9.13)$$

which is certainly true because

$$V''(b^*+; b^*) = -u^2 \left[\frac{\alpha}{\delta} - V(b^*; b^*) \right] = u \quad (9.14)$$

by (9.5).

Finally, to obtain closed-form expressions for the optimal threshold b^* , we can solve (9.5), (8.4), or (8.5) for b^* . Alternatively, we determine the value of b that maximizes (6.14). This leads to

$$b^* = \frac{1}{r-s} \ln \left(\frac{s^2 - us}{r^2 - ur} \right). \quad (9.15)$$

It is interesting to note that the optimal threshold b^* is an increasing function of the ceiling α . As b^* is a function of α via u , we show this in two steps. First, it follows from (9.15) that b^* is an increasing function of u . Second, we note by interpretation that $V(0; 0)/\alpha$ must be a decreasing function of α , from which and formula (6.16) it follows that u is an increasing function of α .

REMARK

It is possible to express condition (9.3) more explicitly in terms of the original parameters of the model. For this purpose we consider first the limiting situation $b^* > 0$, $b^* \rightarrow 0$. From (9.15) we have the condition

$$s^2 - us = r^2 - ur,$$

or

$$u = r + s,$$

which is

$$u = \frac{\beta c - \lambda - \delta}{c} \quad (9.16)$$

by equation (6.6). An equivalent condition is that

$$V(b^*; b^*) = V(0; 0), \quad (9.17)$$

which, by (9.5) and (6.16), is

$$\frac{\alpha}{\delta} + \frac{1}{u} = \frac{-u \alpha}{\beta \delta}, \quad (9.18)$$

or

$$\alpha = \delta \frac{\beta}{-u\beta - u^2}. \quad (9.19)$$

Substitution from (9.16) leads to the condition

$$\alpha = \delta \frac{\beta c^2}{(\lambda + \delta)(\beta c - \lambda - \delta)}. \quad (9.20)$$

The interpretation of this result is as follows. If the denominator is 0 or negative, b^* is 0 for any α . If the denominator is positive, b^* is 0 if α is less than or equal to the expression on the right-hand side of formula (9.20), and b^* is positive if α is greater than this expression. In the limit described in Section 7, formula (9.20) becomes

$$\alpha = \delta \frac{\sigma^2}{2\mu}, \quad (9.21)$$

which corresponds to formula (4.7) in Gerber and Shiu (2006).

10. THE TIME VALUE OF RUIN UNDER A THRESHOLD STRATEGY

As in Section 5, we assume that dividends are paid according to a threshold strategy with parameters $\alpha < c$ and $b > 0$. Let

$$L(x; b) = E[e^{-\delta T} | X(0) = x], \quad x \geq 0, \quad (10.1)$$

denote the expected present value of 1 due at the time of ruin. As a function of δ , this quantity is the *Laplace transform of the time-of-ruin distribution*.

As a function of x , $L(x; b)$ satisfies the following integro-differential equations:

$$cL'(x; b) - (\lambda + \delta)L(x; b) + \lambda \int_0^x L(x - y; b)p(y) dy + \lambda[1 - P(x)] = 0, \quad 0 < x < b, \quad (10.2)$$

and

$$(c - \alpha)L'(x; b) - (\lambda + \delta)L(x; b) + \lambda \int_0^x L(x - y; b)p(y) dy + \lambda[1 - P(x)] = 0, \quad x > b. \quad (10.3)$$

Furthermore,

$$\lim_{x \rightarrow \infty} L(x; b) = 0, \quad (10.4)$$

and $L(x; b)$ is continuous at $x = b$. The function $L(x; b)$ is determined by these conditions.

It follows from equations (10.2) and (10.3) that

$$cL'(b-; b) = (c - \alpha)L'(b+; b). \quad (10.5)$$

Thus, $L'(x; b)$ is not continuous at $x = b$. In the limiting case $\alpha = c$, condition (10.5) becomes

$$L'(b-; b) = 0. \quad (10.6)$$

In the remainder of this section, we calculate $L(x; b)$ for the case where $p(y)$ is exponential as in Section 6. Applying the operator $(d/dx + \beta)$ to equation (10.2) and using (6.2), we see that $L(x; b)$ satisfies the differential equation

$$cL''(x; b) + (\beta c - \lambda - \delta)L'(x; b) - \beta \delta L(x; b) = 0, \quad 0 < x < b. \quad (10.7)$$

Thus,

$$L(x; b) = C_0 e^{rx} + C_1 e^{sx}, \quad 0 \leq x \leq b, \quad (10.8)$$

where the coefficients C_0 and C_1 are to be determined, and r and s are the same as in Section 6, that is, the solutions of the characteristic equation (6.6). Substitution of (10.8) in (10.2) and equating the coefficient of $e^{-\beta x}$ with 0 yields a relation between C_0 and C_1 :

$$\frac{\beta}{\beta + r} C_0 + \frac{\beta}{\beta + s} C_1 = 1. \quad (10.9)$$

Next, we apply the operator $(d/dx + \beta)$ to equation (10.3). This yields the differential equation

$$(c - \alpha)L''(x; b) + [\beta(c - \alpha) - \lambda - \delta]L'(x; b) - \beta \delta L(x; b) = 0, \quad x > b. \quad (10.10)$$

In view of (10.4), we gather that

$$L(x; b) = D e^{ux}, \quad x \geq b, \quad (10.11)$$

where the coefficient D is to be determined and u is the negative solution of the characteristic equation (6.11). The continuity of the function $L(x; b)$ at $x = b$ yields the condition

$$C_0 e^{rb} + C_1 e^{sb} = D e^{ub}. \quad (10.12)$$

Finally, we substitute (10.8) and (10.11) in (10.3). This leads to the condition

$$C_0 \frac{e^{rb}}{\beta + r} + C_1 \frac{e^{sb}}{\beta + s} = D \frac{e^{ub}}{\beta + u}. \quad (10.13)$$

Equations (10.9), (10.12), and (10.13) are three conditions for determining C_0 , C_1 , and D . They can be solved as follows. Multiplying equation (10.13) by $(\beta + u)$ and subtracting the resulting equation from equation (10.12), we get

$$C_0 e^{rb} \frac{r - u}{\beta + r} + C_1 e^{sb} \frac{s - u}{\beta + s} = 0. \quad (10.14)$$

Solving equations (10.9) and (10.14) simultaneously, we have

$$C_0 = \frac{\beta + r}{\beta} \frac{e^{sb}(u - s)}{e^{rb}(r - u) + e^{sb}(u - s)}, \quad (10.15)$$

$$C_1 = \frac{\beta + s}{\beta} \frac{e^{rb}(r - u)}{e^{rb}(r - u) + e^{sb}(u - s)}. \quad (10.16)$$

Thus, (10.8) becomes

$$L(x; b) = \frac{1}{\beta} \frac{(\beta + r)(u - s)e^{rx+sb} + (\beta + s)(r - u)e^{sx+rb}}{(r - u)e^{rb} + (u - s)e^{sb}}, \quad 0 \leq x \leq b. \quad (10.17)$$

In particular,

$$L(b; b) = \frac{1}{\beta} \frac{(r - s)(\beta + u)}{(r - u)e^{-sb} + (u - s)e^{-rb}}. \quad (10.18)$$

With this, we can express $L(x; b)$ for $x \geq b$ as

$$L(x; b) = L(b; b)e^{u(x-b)}, \quad x \geq b. \quad (10.19)$$

REMARKS

1. As explained in Section 7, the Brownian motion model can be obtained as a limit. For $\beta \rightarrow \infty$, (10.17) yields formula (6.12) in Gerber and Shiu (2006), where r , s , and u are now solutions of equations (7.4) and (7.5).
2. Suppose that $(c - \alpha) > E[S(1)]$, so that the probability of ruin, $\psi(x; b)$, is less than 1. We obtain $\psi(x; b)$ from $L(x; b)$ as the limit $\delta \rightarrow 0$. Note that in the limit, $r = 0$, and equations (6.6) and (6.11) become linear equations for s and u , respectively, yielding

$$s = -\left(\beta - \frac{\lambda}{c}\right), \quad (10.20)$$

$$u = -\left(\beta - \frac{\lambda}{c - \alpha}\right). \quad (10.21)$$

With these substitutions, formulas (10.17)–(10.19) lead to closed-form expressions for $\psi(x; b)$. See also Section VII.1 of Asmussen (2000).

3. Consider the limiting case $\alpha = c$. Then, we conclude from (10.6) and (10.8) that

$$L(x; b) = \kappa(r e^{sx+rb} - s e^{rx+sb}), \quad 0 \leq x \leq b, \quad (10.22)$$

where the constant κ is determined from equation (10.9):

$$\kappa \left(-\frac{\beta}{\beta + r} s e^{sb} + \frac{\beta}{\beta + s} r e^{rb} \right) = 1. \quad (10.23)$$

Thus,

$$L(x; b) = \frac{(\beta + r)(\beta + s)}{\beta} \gamma(r e^{sx+rb} - s e^{rx+sb}), \quad 0 \leq x \leq b, \quad (10.24)$$

with γ given by (6.8). This result can be found in Segerdahl (1970, eq. [18.5]), Gerber (1979, p. 150, eq. [2.4]), Lin, Willmot, and Drekić (2003, eq. [6.3]), and Dickson and Waters (2004, eq. [4.4]).

4. Appendix B sketches how $L(x; b)$ can be calculated if $p(y)$ is a mixture of exponential densities.

11. RESULTS FOR $x = b = 0$

Suppose that the threshold strategy with parameter $b = 0$ is applied and that the initial surplus is $x = 0$. Then closed-form formulas are available for *arbitrary* claim amount density functions.

From formula (3.9) in Gerber and Shiu (1998), it follows that

$$L(0; 0) = E[e^{-\delta T} | X(0) = b = 0] = 1 - \frac{\delta}{(c - \alpha)u_0}, \quad (11.1)$$

where u_0 is the positive solution of Lundberg's fundamental equation

$$(c - \alpha)\xi - (\lambda + \delta) + \lambda\hat{p}(\xi) = 0, \quad (11.2)$$

with $\hat{p}(\xi)$ being the Laplace transform of the density function $p(y)$. Gerber and Shiu (p. 77) have pointed out that their formula (3.3) holds even if the safety loading is not positive; thus equation (11.1) holds as long as $c > \alpha$. Hence,

$$V(0; 0) = \alpha E \left[\frac{1 - e^{-\delta T}}{\delta} \mid X(0) = b = 0 \right] = \alpha \frac{1 - L(0; 0)}{\delta} = \frac{\alpha}{(c - \alpha)u_0}. \quad (11.3)$$

In the particular case of an exponential claim amount probability density function $p(y)$, equation (11.2) boils down to the quadratic equation (6.11). Its solutions are $u_0 > 0$ and $u < 0$. Then, by observing that

$$u u_0 = -\frac{\beta\delta}{c - \alpha}, \quad (11.4)$$

we can reconcile (6.16) with (11.3).

From equation (5.2) with $x = b = 0$ and (11.3), we obtain

$$V'(0+; 0) = \frac{1}{c - \alpha} [(\lambda + \delta)V(0; 0) - \alpha] = \frac{\alpha}{c - \alpha} \left[\frac{\lambda + \delta}{(c - \alpha)u_0} - 1 \right]. \quad (11.5)$$

Hence, $V'(0+; 0) \leq 1$ is equivalent to the condition

$$\frac{\lambda + \delta}{c} \leq \left(\frac{c}{\alpha} - 1 \right) u_0. \quad (11.6)$$

Therefore, in cases where the optimal strategy is a threshold strategy, condition (11.6) is equivalent to $b^* = 0$.

APPENDIX A

The purpose of this appendix is to show how the value of a threshold strategy can be calculated if the individual claim amount density is a *mixture of exponential densities*,

$$p(y) = \sum_{i=1}^n A_i \beta_i e^{-\beta_i y}, \quad y > 0, \quad (A.1)$$

with $0 < \beta_1 < \beta_2 < \dots < \beta_n$, $A_i > 0$, for $i = 1, 2, \dots, n$, and $\sum_{i=1}^n A_i = 1$. The case $n = 1$ was treated in Section 6. The Laplace transform of (A.1) is

$$\hat{p}(\xi) = \sum_{i=1}^n A_i \frac{\beta_i}{\beta_i + \xi}. \quad (\text{A.2})$$

Although the Laplace transform of $p(y)$ only exists for $\text{Re } \xi > -\beta_1$, for the remainder of this paper we extend the definition of $\hat{p}(\xi)$ to be the rational function given on the right-hand side of (A.2).

Assume $b > 0$; formulas for $b = 0$ will be obtained as appropriate limits. If we apply the operator

$$\prod_{i=1}^n \left(\frac{d}{dx} + \beta_i \right) \quad (\text{A.3})$$

to equation (5.6) and use (6.2) repeatedly, we see that the function $h(x)$ satisfies a homogeneous differential equation (with constant coefficients) of order $n + 1$. Hence, we set

$$h(x) = \sum_{k=0}^n C_k e^{\rho_k x}. \quad (\text{A.4})$$

Substitution of (A.1) and (A.4) in the integro-differential equation (5.6) yields the condition that

$$c \sum_{k=0}^n C_k \rho_k e^{\rho_k x} - (\lambda + \delta) \sum_{k=0}^n C_k e^{\rho_k x} + \lambda \sum_{i=1}^n \sum_{k=0}^n A_i C_k \frac{\beta_i}{\beta_i + \rho_k} (e^{\rho_k x} - e^{-\beta_i x}) = 0. \quad (\text{A.5})$$

Equating the coefficient of $e^{\rho_k x}$ with 0, we obtain the condition that

$$c \rho_k - (\lambda + \delta) + \lambda \sum_{i=1}^n A_i \frac{\beta_i}{\beta_i + \rho_k} = 0, \quad k = 0, 1, \dots, n. \quad (\text{A.6})$$

Thus, $\rho_0, \rho_1, \dots, \rho_n$ are the solutions of

$$c\xi - (\lambda + \delta) + \lambda\hat{p}(\xi) = 0, \quad (\text{A.7})$$

which is *Lundberg's fundamental equation*. Analogous of formula (13.6.15) of Bowers et al. (1997), we have

$$-\beta_n < \rho_n \cdots < -\beta_2 < \rho_2 < -\beta_1 < \rho_1 < 0 < \rho_0, \quad (\text{A.8})$$

showing that $\rho_0, \rho_1, \dots, \rho_n$ are distinct numbers.

Also, equating the coefficient of $e^{-\beta_i x}$ with 0, we obtain the condition

$$\sum_{k=0}^n C_k \frac{1}{\beta_i + \rho_k} = 0, \quad i = 1, \dots, n. \quad (\text{A.9})$$

This is a system of n linear equations for the $(n + 1)$ coefficients C_0, C_1, \dots, C_n . Recall that $h(x)$ is determined only up to a multiplicative constant. Chan, Gerber, and Shiu (2006, eq. [D.31]) give the formula

$$C_k = h(0) \frac{\prod_{i=1}^n (\rho_k + \beta_i)}{\prod_{j=0, j \neq k}^n (\rho_k - \rho_j)}. \quad (\text{A.10})$$

In the following, we simply let C_0, C_1, \dots, C_n denote a particular solution of (A.9).

Now we apply the operator (A.3) to equation (5.2) and use (6.2) repeatedly. This way, we see that the function $V(x; b)$, $x > b$, satisfies a linear differential equation (with constant coefficients) of order $n + 1$. A particular solution is, of course, the asymptotic value α/δ . Hence, we set

$$V(x; b) = \frac{\alpha}{\delta} + \sum_{k=0}^n D_k e^{u_k x}, \quad x \geq b. \quad (\text{A.11})$$

We now substitute this expression, (5.7) with $h(x)$ given by (A.4), and (A.1) in the integro-differential equation (5.2). This yields the condition

$$\begin{aligned} & \alpha + (c - \alpha) \sum_{k=0}^n D_k u_k e^{u_k x} - (\lambda + \delta) \left(\frac{\alpha}{\delta} + \sum_{k=0}^n D_k e^{u_k x} \right) + \gamma \lambda \sum_{i=1}^n \sum_{k=0}^n A_i C_k \frac{\beta_i}{\beta_i + \rho_k} [e^{\rho_k b - \beta_i(x-b)} - e^{-\beta_i x}] \\ & + \lambda \frac{\alpha}{\delta} \sum_{i=1}^n A_i [1 - e^{-\beta_i(x-b)}] + \lambda \sum_{i=1}^n \sum_{k=0}^n A_i D_k \frac{\beta_i}{\beta_i + u_k} [e^{u_k x} - e^{u_k b - \beta_i(x-b)}] = 0, \quad x > b. \end{aligned} \quad (\text{A.12})$$

First we note that the constant term on the left-hand side is 0; this does not yield a new condition. Now equating the coefficient of $e^{u_k x}$ with 0, we get the condition that

$$(c - \alpha)u_k - (\lambda + \delta) + \lambda \sum_{i=1}^n A_i \frac{\beta_i}{\beta_i + u_k} = 0, \quad k = 0, 1, \dots, n. \quad (\text{A.13})$$

This means that u_0, u_1, \dots, u_n are the roots of equation (11.2). Similar to inequalities (A.8), we have the inequalities

$$-\beta_n < u_n < \dots < -\beta_2 < u_2 < -\beta_1 < u_1 < 0 < u_0. \quad (\text{A.14})$$

It follows from the asymptotic formula (5.3) that $D_0 = 0$. Finally, we equate the coefficient of $e^{-\beta_i x}$ with 0. This leads to the condition

$$\gamma \sum_{k=0}^n C_k \frac{1}{\beta_i + \rho_k} e^{\rho_k b} = \frac{\alpha}{\delta} \frac{1}{\beta_i} + \sum_{k=1}^n D_k \frac{1}{\beta_i + u_k} e^{u_k b}, \quad i = 1, \dots, n. \quad (\text{A.15})$$

These are n linear equations for γ, D_1, \dots, D_n . The remaining condition follows from the continuity of the function $V(x; b)$ at $x = b$:

$$V(b-; b) = V(b+; b),$$

or

$$\gamma \sum_{k=0}^n C_k e^{\rho_k b} = \frac{\alpha}{\delta} + \sum_{k=1}^n D_k e^{u_k b}. \quad (\text{A.16})$$

Finally, we consider the case $b = 0$. Then

$$V(x; 0) = \frac{\alpha}{\delta} + \sum_{k=1}^n D_k e^{u_k x}, \quad x \geq 0. \quad (\text{A.17})$$

The coefficients D_1, \dots, D_n are now the solution of a simpler system of linear equations:

$$\sum_{k=1}^n \frac{1}{\beta_i + u_k} D_k = -\frac{\alpha}{\delta \beta_i}, \quad i = 1, \dots, n. \quad (\text{A.18})$$

To see this, set $b = 0$ in (A.15) and use (A.9). We note that the coefficient matrix of (A.18) is a *Cauchy matrix* (Knuth 1973, p. 36; Pólya and Szegő 1976, p. 279). An explicit expression for the entries in the inverse of a Cauchy matrix can be found in Gerber and Shiu (2005, p. 67, eq. [A.2]).

REMARK

The family of *combinations* of exponential densities (where the A_i 's in (A.1) are not necessarily positive) is much richer than the family of mixtures of exponential densities. If $p(y)$ is a combination of exponential densities, the value of a threshold strategy can be calculated essentially by the same method, but two points should be kept in mind: Some of the solutions of Lundberg's equations can be complex, and for exceptional constellations of the parameter values, some roots may be multiple roots.

APPENDIX B

The purpose of this appendix is to indicate how $L(x; b)$ can be calculated if $p(y)$ is a mixture of exponential densities. If we apply the operator (A.3) to (10.2), we see that $L(x; b)$, $0 < x < b$, satisfies

a homogeneous linear differential equation (with constant coefficients) of order $n + 1$. Hence we set

$$L(x; b) = \sum_{k=0}^n C_k e^{\rho_k x}, \quad 0 \leq x \leq b. \quad (\text{B.1})$$

Substitution in (10.2) yields the condition

$$c \sum_{k=0}^n C_k \rho_k e^{\rho_k x} - (\lambda + \delta) \sum_{k=0}^n C_k e^{\rho_k x} + \lambda \sum_{i=1}^n \sum_{k=0}^n A_i C_k \frac{\beta_i}{\beta_i + \rho_k} (e^{\rho_k x} - e^{-\beta_i x}) + \lambda \sum_{i=1}^n A_i e^{-\beta_i x} = 0. \quad (\text{B.2})$$

Equating the coefficient of $e^{\rho_k x}$ with 0, we obtain condition (A.6). Thus, $\rho_0, \rho_1, \dots, \rho_n$ are defined as in Appendix A, that is, as the solutions of Lundberg's fundamental equation (A.7). Now, equating the coefficient of $e^{-\beta_i x}$ with 0, we obtain the condition

$$\sum_{k=0}^n C_k \frac{\beta_i}{\beta_i + \rho_k} = 1, \quad i = 1, \dots, n. \quad (\text{B.3})$$

We remark that, if $b = \infty$, then $C_0 = 0$, and

$$C_i = \left(\prod_{h=1, h \neq i}^n \frac{\rho_h}{\rho_h - \rho_i} \right) \left(\prod_{k=1}^n \frac{\beta_k + \rho_i}{\beta_k} \right), \quad i = 1, \dots, n, \quad (\text{B.4})$$

by Gerber and Shiu (2005, eq. [5.35]). Under the positive security-loading condition, the limiting case of $\delta \rightarrow 0$ gives $L(x; \infty) = \psi(x)$, the probability of ruin. In this case, formula (B.4) can be found in Täcklind (1942).

Applying the operator (A.3) to equation (10.2), we see that $L(x; b)$, $x > b$, satisfies also a homogeneous linear differential equation (with constant coefficients) of order $n + 1$. Hence, we set

$$L(x; b) = \sum_{k=0}^n D_k e^{u_k x}, \quad x \geq b. \quad (\text{B.5})$$

Substitution of (B.1) and (B.5) in equation (10.3) yields the condition

$$\begin{aligned} (c - \alpha) \sum_{k=0}^n D_k u_k e^{u_k x} - (\lambda + \delta) \sum_{k=0}^n D_k e^{u_k x} + \lambda \sum_{i=1}^n \sum_{k=0}^n A_i C_k \frac{\beta_i}{\beta_i + \rho_k} [e^{\rho_k b - \beta_i(b-x)} - e^{-\beta_i x}] \\ + \lambda \sum_{i=1}^n \sum_{k=0}^n A_i D_k \frac{\beta_i}{\beta_i + u_k} [e^{u_k x} - e^{u_k b - \beta_i(b-x)}] + \lambda \sum_{i=1}^n A_i e^{-\beta_i x} = 0, \quad x > b. \end{aligned} \quad (\text{B.6})$$

Inspection of the coefficient of $e^{u_k x}$ reveals that u_0, u_1, \dots, u_n are the same as those in Appendix A. From (10.4) it follows that $D_0 = 0$. Note that because of (B.3), the coefficient of $e^{-\beta_i x}$ on the left-hand side of (B.6) vanishes in any case. However, equating the coefficient of $e^{\beta_i x}$ with 0, we obtain the condition

$$\sum_{k=0}^n C_k \frac{1}{\beta_i + \rho_k} e^{\rho_k b} = \sum_{k=1}^n D_k \frac{1}{\beta_i + u_k} e^{u_k b}, \quad i = 1, 2, \dots, n. \quad (\text{B.7})$$

Finally, from the continuity of $L(x; b)$ at $x = b$, it follows that

$$\sum_{k=0}^n C_k e^{\rho_k b} = \sum_{k=1}^n D_k e^{u_k b}. \quad (\text{B.8})$$

In conclusion, (B.3), (B.7), and (B.8) constitute a system of $2n + 1$ linear equations from which the coefficients $C_0, C_1, \dots, C_n, D_1, \dots, D_n$ can be determined.

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