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PARAMETRIC EMPIRICAL BAYES AND CREDIBILITY THEORY

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The current view of empirical Bayes inference models data and parameters alike with two families of distributions: one family for data, and one for the unknown parameters, with the latter involving either parametric prior distributions (PEB) or nonparametric prior distributions (NPEB). The (prior) distributions of the unknown parameters is assumed to be restricted to a class Π having just one member, while frequentist statistical inference allows Π to contain all possible prior distributions. Empirical Bayes inference covers involving limited knowledge about Π , giving the statistician flexibility to develop new statistical procedures.

This paper shows credibility theory and PEB theory are intimately related, and reviews and applies recent PEB theory to the credibility situation, for the normal and other familiar distributions.

FOUNDATIONS

Empirical Bayes involves 2 families of stochastic processes, one for the data (distribution, likelihood) and one for the parameters (prior, superpopulation).

Parametric ($\alpha \in \alpha$) Empirical Bayes (PEB) Paradigm: $\Pi = \{\pi_\alpha : \alpha \in \alpha\}$ is known

	<u>Descriptive Model</u>	<u>Inferential Model</u>
Observed Data	(1) $Y \theta \sim f(y \theta)$ (Likelihood)	(1*) $Y \sim \bar{f}_\alpha(y), \alpha \in \alpha$
Unobserved Parameters (prior)	(2) $\theta \sim g_\alpha(\theta), \alpha \in \alpha$	(2*) $\theta Y \sim \bar{g}_\alpha(\theta y)$

Evaluations involve two integrals: $r(\alpha, t) = E_\alpha E_\theta L(\theta, t(Y))$

e.g.: $E_\alpha E_\theta (\hat{\theta}(Y) - \theta)^2 = \text{Bayes risk } (\alpha) + E(\hat{\theta}(Y) - \hat{\theta}_\alpha(Y))^2, \hat{\theta}_\alpha = \text{Bayes Estimate}$

Nonparametric Empirical Bayes (Robbins, $k \rightarrow \infty$), if $\alpha = \pi_1$

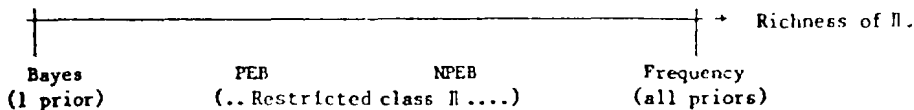


Table 1

Parameters to be Estimated	Unbiased Estimate	Variance	Restricted Model Estimate	Concomitant Information Vector (Dimensional)
θ_1	Y_1	V_1	$\hat{\theta}_1$	z_1
θ_2	Y_2	V_2	$\hat{\theta}_2$	z_2
\vdots	\vdots	\vdots	\vdots	\vdots
θ_k	Y_k	V_k	$\hat{\theta}_k$	z_k

Distributions: Descriptive Form

(1) $Y_i | \theta_i \sim N(\theta_i, V_i), i = 1, \dots, k$ independently

(2) $\theta_i | \beta, A \sim N(z_i' \beta, A) i = 1, \dots, k$

Π : $r + 1$ dimensional

$\leftarrow (A, \beta)$ unknown

Inferential Form

(1*) $Y_i | \beta, A \overset{\text{ind}}{\sim} N(z_i' \beta, V_i + A)$

(2*) $\theta_i | Y_i, \beta, A \overset{\text{ind}}{\sim} N(\theta_i^*, V_i(I - B_i))$

$$\theta_i^* = (I - B_i)Y_i + B_i z_i' \beta$$

$$B_i = V_i / (V_i + A)$$

INTERVAL ESTIMATES:

$$\hat{\theta}_i \pm z s, \quad P(\hat{\theta}_i - z s \leq \theta_i \leq \hat{\theta}_i + z s) \geq 2\Phi(z) - 1 \quad \text{all } \alpha = (A, \beta)$$

Estimate of $\hat{\theta}_i$

$$\hat{\theta}_i = (I - \hat{B}_i)Y_i + \hat{\beta}_i z_i' \hat{\beta}$$

$$\hat{\beta} = (Z'DZ)^{-1} Z'DY$$

$$\hat{B}_i = ((k - r - 2)/(k - r)) V_i / (V_i + \hat{A})$$

$$\hat{A} = \frac{\sum W_i ((k/(k - r))(Y_i - z_i' \hat{\beta})^2 - V_i)}{\sum W_i}$$

force $\hat{A} \geq 0$

$$D = \text{Diag}(W_1, \dots, W_k) \quad W_i = 1/(V_i + \hat{A})$$

Estimate of Variability in $\hat{\theta}_i$

$$s_i^2 = V_i \{1 - ((k - r_i)/(k)) \hat{B}_i\} + v_i (Y_i - z_i' \hat{\beta})^2$$

$$v_i = (2/(k - r - 2)) \hat{B}_i^2 (V_i + \hat{A}) / (V_i + \hat{A})$$

$$\hat{r}_i = k W_i [Z(Z'DZ)^{-1} Z']$$

$$V = \sum W_i V_i / \sum W_i$$

MSE if $V_1 = \dots = V_k$: "EB Minimax", but not (Frequentist) minimax.

$$E(\hat{\theta}_i - \theta_i)^2 = E E_{\theta_i}(\hat{\theta}_i - \theta_i)^2 = V(1 - ((k - r_i - 2)/k) E \hat{B}_i), \quad r_i = k \hat{z}_i' (Z'Z)^{-1} \hat{z}_i, \quad \bar{r} > r.$$

SAS PROGRAM

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* I=1 TO K;
* IZ ((B*(A-B))>EPSILON) AND ((A>0) CB (1-1));
A1=A;
* W=1/(V+A); * W;
* D=DIAG(W); * D;
* Z=1/(V*(Z'*OUT*Z)+2);
* W2=W*W; * W;
* A=SUB(W*((B*(K-B))+(Y-ND)*2))-W)/SOP(W);
* PRINT A;
END;
    
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IF (ACO) THEN B=0;
B=((K-B-2)/K)*V/(V+A); * B;
* STAR=((1-B)*E)*B/PD; * B;
* VBAR=SUB(V+W)/SOP(W); * V;
* SHALL1=(2*W/(K-B-2))*B*B*(VBAR+A)/(V+A); * V;
* WHALF=SQRT(SHALL1);
* SHALL2=K*V*CDIAG(P)/V+A; * A;
* SIGSTAR2=V*((1-((K-SHALL1)/K)*B))*1/(Y-ND)*42; * B;
* SIGSTAR=SQRT(SIGSTAR2); * A;
    
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Exchangeable Priors:

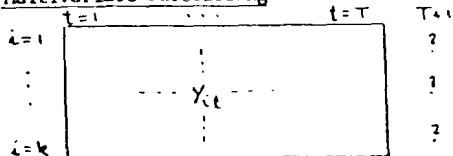
(a) Equal Variances (exposures)



(b) Unequal Variances



Multivariate Forecasting:



Ranking and Selecting the Best: "Ensemble Information"

- i) Toxoplasmosis Rates: City 2 worse than City 1.
- ii) Was Frank O'Conner better than Ruth and Cobb?
- iii) Taxicab Example.

Non-Normal Data: Exchangeable data and Exchangeable priors. (NEF-VDF)

$$X_i | \mu_i \sim \text{NEF}(\eta_i, V(\mu_i)/n), \quad i = 1, \dots, k.$$

$$\mu_i \sim \text{CP}(\eta_i, \tau_i^2 = V(\eta_i)/(m_i + v_i)), \quad i = 1, \dots, k.$$

$$E\mu_i | X_i = (1 - B)X_i + B\bar{X}$$

$$B = \frac{v_2}{n + v_2} \frac{k-1}{k} + \frac{n}{n + v_2} E \left\{ \frac{V(\bar{X})}{n} \right\} \frac{k-1}{ES}$$

$$\hat{B} = \frac{v_2}{n + v_2} \frac{k-1}{k} + \frac{n}{n + v_2} \hat{B}_{JS}$$

$$E\{V(\bar{X})\} = (k-1)/ES \approx E\{V(\bar{X})\} = (k-3)/S.$$

$\hat{B}_{JS} = (k-3)V(\bar{X})/nS$, the naive extension of the James Stein shrinking factor.

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